

0.04Hz~200kHz 5 $\mu$ s response  
PERIOMATIC™ Processing

# KAZ-723A

## High Speed Frequency-to-Voltage (F/V) Converter for measurement and analysis of rotary motion

The analog output is updated once for each incoming pulse.



Employing rotary encoder, optical sensor or gear speed sensor, KAZ-723A converts the frequency (detected pulse) into analog voltage within 5  $\mu$  s of processing response. KAZ-723A covers 0.04Hz to 200kHz by PERIOMATIC™ process.

That is ——— KAZ-723 is Frequency to Voltage Converter (F/V converter)

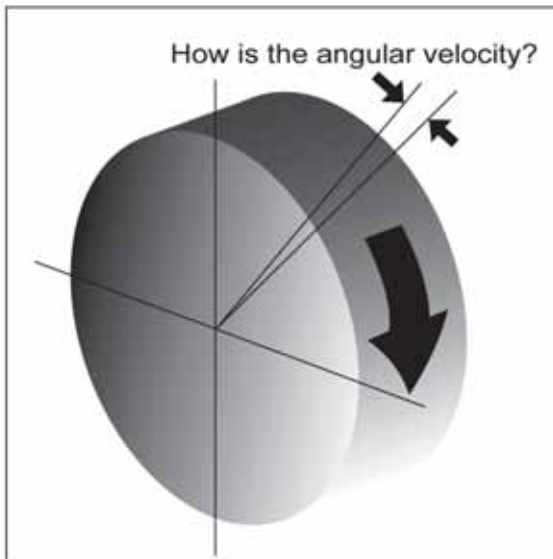
KAZ-723A can be used to obtain several solutions about frequency measurement for angular velocity, frequency and speed fluctuation.

### Applications

Measurement and Analysis of Rotary Motion, Mechanical Action, Sudden Stop Behaviors, Flow Speed, Ultra Low Speed, Reducer, Speed Converter, Speed Fluctuation.

ROBOTS COPY-MACHINE AUTOMOBILE CASTING-MACHINE STIRRER FLOW-CONTROL  
SPEED-GOVERNOR ELECTRIC-POWER-PLANT OIL-PRESSURE-MACHINE ENGINE BRAKE  
LINEAR ACTUATOR PULSE MOTOR SEMICONDUCTOR MACHINE

# KAZ-723A F/V CONVERTER with DEVIATION OUTPUT



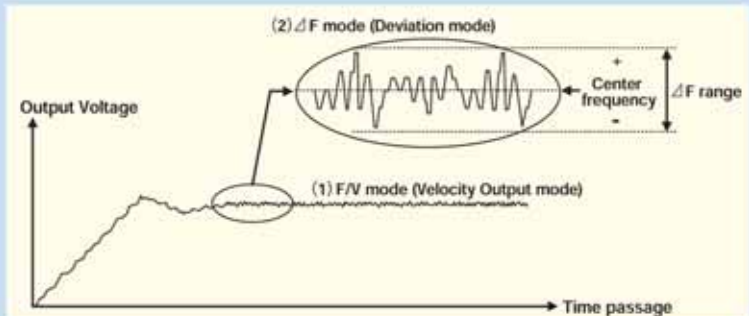
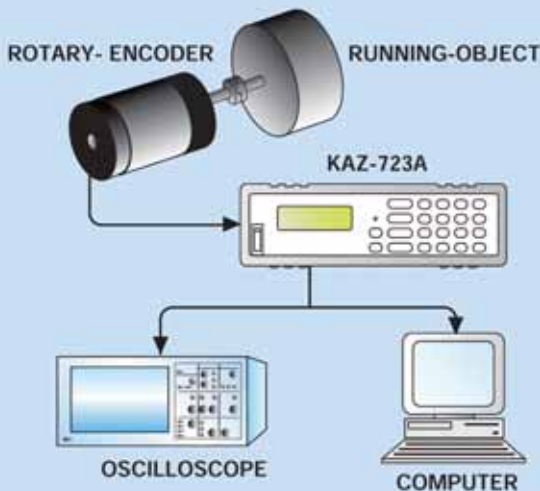
You can catch angular velocity precisely on real time while rotating.

You can catch velocity about each 1 degree, using rotary encoder 360 pulse/r to detect rotation. KAZ-723A converts detected pulse into analogue voltage signal on real time.

The technology PERIOMATIC™ that is known as interval method has been put to practical use by COCORESEARCH leading in the world

## Which data is useful for you F/V or $\Delta F$

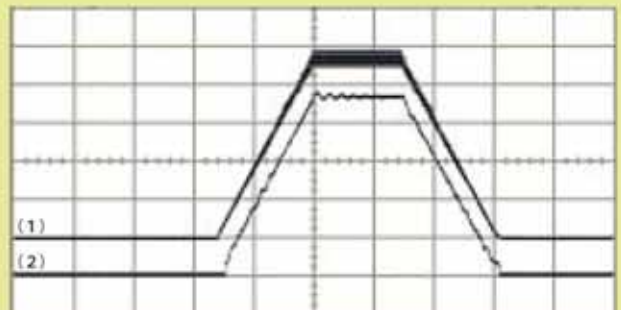
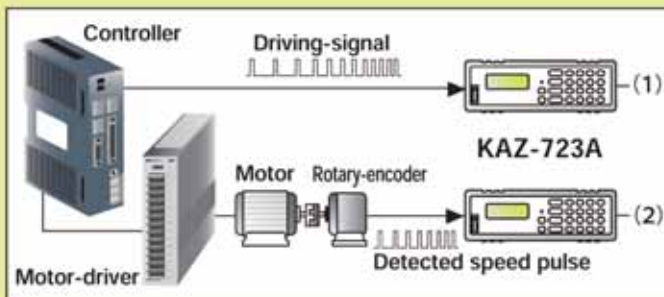
KAZ-723 enables to switch as you wish.



(1) The output becomes a voltage proportional to input frequency on F/V mode.

(2) The  $\pm$  output becomes a voltage proportional to deviation of a settled frequency and a settled sensibility ( $\Delta F$  range). The applicable center frequency is 1Hz~100kHz.  $\Delta F$  range has 8 steps,  $\pm 0.5\% \sim \pm 100\%$ .

## An Example of Driving Pulse and Motor behavior for a Pulse motor



The output shows driving pulse(1) and the hunting of the motor(2).

### CONDITIONS

#### KAZ-723A (1)

Mode: F/V mode  
Settled Full scale Frequency: 70kHz  
Settled Analogue output: 0 to 10V

#### KAZ-723A (2)

Mode: F/V mode  
Full scale Frequency : 7kHz  
Analogue output: 0 to 10V

#### Input Signal

Input Frequency (1) : 0 to 65kHz  
Input Frequency (2) : 0 to 6.5kHz

#### Oscilloscope

Time axis : 50ms/div.  
Voltage axis : 2V/div.

## Features

### Wide Range 0.04Hz~200kHz

In the range of 0.03Hz to 120kHz KAZ-723A can operate within one pulse response. The full scale value of F/V mode and the center frequency of  $\Delta F$  mode can be set in each 1 Hz.

### Deviation Output ( $\Delta F$ mode)

Corresponding to settled center frequency, the fluctuation (deviation) of frequency is converted into analogue  $\pm 10V$  ( $\pm 5V$  available) of deviation outputs. The sensibility of  $\Delta F$  mode can be chosen from 8-steps of  $\pm 0.5\%$  to  $\pm 100\%$ . This  $\Delta F$  mode is used to check fluctuation of rotary motion mainly.

### High Resolution

The input within 6.25ns(160MHz Equivalent) resolution. output stage, 16-bit D/A converter.

### High Response (within 5 $\mu s$ over all)

The process spends less than only 3 $\mu s$ . Even an over all containing isolation, D/A conversion and analogue output it doesn't over 5 $\mu s$ .

### Manyfold Signal available

A Logic square wave, a NPN open-collector signal, a wide use AC-signal and a balanced line-driver signal are applicable.

### Pulse Divider

Pulse dividing can be set from 1 to 64. The pulse dividing is effective to measure intermittent incoming pulses.

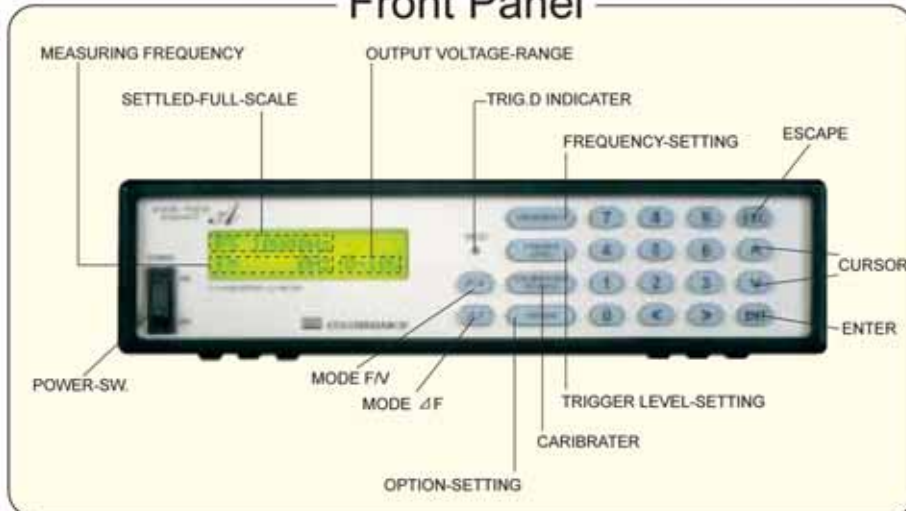
### Moving Average

To avoid delay effect of averaging, the moving average can respond each input change keeping average effect. KAZ-723A is provided 1 to 32 register of moving data.

### PERIOMATIC technology

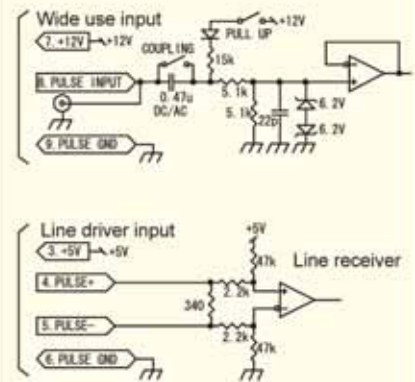
The KAZ-723A has the advanced forecast computation, PERIOMATIC™, which was invented by Cocoresearch. So the analog output can follow even so heavy fluctuation. The PERIOMATIC™ also includes stop (zero speed) forecasting, so the KAZ-723A can respond to sudden stop of the incoming pulses.

## Front Panel



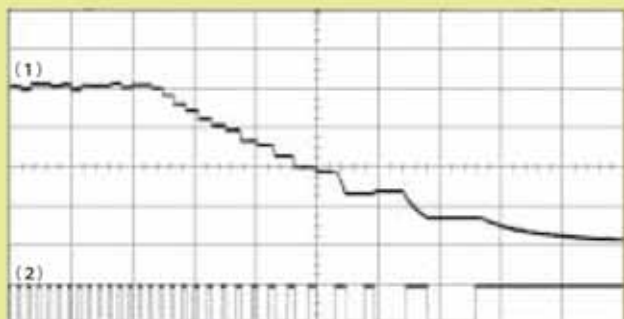
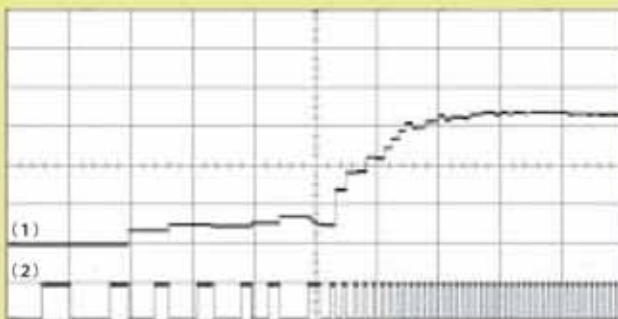
## Input Port

Isolated block



The Pulse GND is isolated to Frame.

## An Example of Start Up and Stop behavior for a reciprocal engine



### CONDITIONS

**KAZ-723 (1)**  
 Mode: F/V mode  
 Settled Full scale Frequency: 150Hz  
 Settled Analogue output : 0 to 10V  
**Input Signal (2)** Input Frequency: 0 to 100Hz  
**Oscilloscope**  
 Time axis : 100ms/div.  
 Voltage axis (1): 2V/div.  
 Voltage axis (2): 10V/div.

The start up behavior (LEFT)  
 The stop behavior (RIGHT)



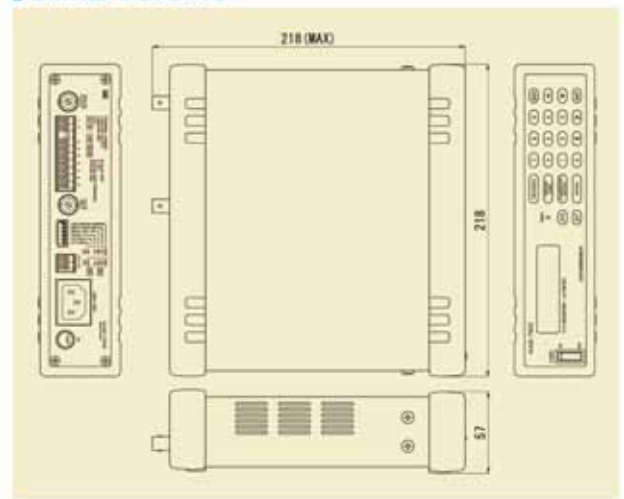
### CONDITIONS

**KAZ-723 (1)**  
 Mode: F/V mode  
 Settled Full scale Frequency: 150Hz  
 Settled Analogue Output : 0 to 10V  
**Input Signal (2)** Input Frequency : 60 to 0Hz  
**Oscilloscope**  
 Time axis : 100ms/div.  
 Voltage axis (1): 1V/div.  
 Voltage axis (2): 10V/div.

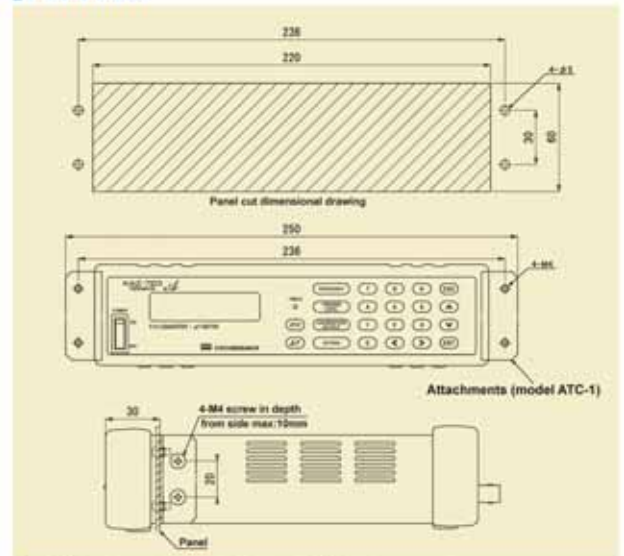
## SPECIFICATIONS

	Name Model Measurement method	F/V Converter KAZ-723 A PERIOMATIC™ processing
Input	Number of inputs Input frequency range Resolution Input circuit (1)General input signals (Wide use signal)	1 0.04Hz—200kHz 6.25ns (160MHz equivalent)
	(2)Line driver input	Input signal : Logic / zero cross(AC) Trigger level : 0.0—9.9V(accuracy ± 0.1 V max.) Input sensitivity : Min. 0.2 V p-p Allowable rating : ±80V Input resistance : Under non-pull-up 10kΩ Under pull-up +5V.6kΩ Input coupling : DC/AC AC coupling frequency characteristic : 35Hz(-3dB, 6dB/oct) Low-pass filter : None/15kHz(-3dB, 6dB/oct)/ 1.5kHz(-3dB, 6dB/oct) Input connector : BNC connector / screwless terminal block (loop through)
	Input pulse width Trigger direction Input indicator	Min. 2μs (both H level and L level) Rise/Fall (selectable) TRIG LED : Flashes during pulse input (continuously lit for high-speed pulse)
	Power supply for sensor	+5V : Max.150mA +12V : Max.120mA
Display	Display Frequency display digits Zero display Display update time Frequency display accuracy Display unit	16×2 character dot matrix LCD (LED backlight illumination) 6 digits Leading zero suppressed 0.3s ±100ppm / °C ±1digit @23°C Hz / rpm
Processing	Measurement mode Operation time Input pulse dividing Output moving average Auto-zero Set value storage	F/V (speed output) / ΔF (deviation output) Max.3μs 1—64 (by software) 1—32 (average of input pulse number) 5 stages(DYNAMICFORECAST™) Non-volatile memory (EEPROM)
Analog Output	Number of outputs F/V mode ΔF (deviation output) mode	1 Full scale setting range : 1Hz—200kHz Output voltage range : 0—10V / 0—5V / 1—5V Center frequency setting range : 1Hz—100kHz Output voltage range : ±10V / ±5V ΔF sensibility range : ±0.5% / ±1% / ±2% / ±5% / ±10% / ±20% ±50% / ±100%
	Output resolution Calibration reference output Output response time Temperature fluctuation Output accuracy Linearity Load resistance Output zero adjustment range Output connector	16bit (about ±10.8V) +100% / 0% / -100% (-100% in ΔF mode only) Max. 5 μs (90% response) Max. ± 200ppm/°C Max. ± 0.1% of full scale Max. ± 0.1% Min. 4.7kΩ ±200mV BNC connector / screwless terminal block (loop through)
General	Power supply input Electric power consumption Isolation	AC85V—250V (50Hz/60Hz) Max.30VA Sensor power source and signal input / analog output / power supply input / housing
	Outside dimensions Weight Operating temperature & humidity limits Storage temperature & humidity limits Operating ambient atmosphere	57mm (H) ×218mm (W) ×218mm (D) (including protrusions) Approximately 1.8kg 0°C—+40°C / Max.85%HR (no dewing) -10°C—+60°C / Max.85%HR (no dewing) No corrosive gas and explosive gas

## DIMENSIONS



## FITTING



A pair of Attachment for panel fitting (model ATC-1) is as a option.

## TERMINAL

BNC Connector		Screwless Terminal Block									
ANALOG OUTPUT	PULSE INPUT (GENERAL)	1	2	3	4	5	6	7	8	9	F.G.
		ANALOG OUTPUT	ANALOG GND	+5V	PULSE INPUT	PULSE INPUT	PULSE GND	+12V	PULSE INPUT	PULSE GND	
		ANALOG OUTPUT			PULSE INPUT(LINE DRIVER)			PULSE INPUT(GENERAL)			
Analog output	General input signal	Analog output			Line driver input			General input signal			

■If there is a possibility of secondary damages that may result from operation or mal-function of this product, take appropriate preventive measures to ensure safety.(fail-safe structure)

■Specifications are subject to change without any obligation on the part of manufacturer.

# WE SUPPORT PRECISE SPEED ANALYSIS

THE INTERVAL METHOD  
BEGAN TO USE FROM  
COCORESEARCH BY THE  
NAME OF PERIOMATIC™



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